// Set Right Motors to forward

//Right Back

digitalWrite(RB\_in1, LOW);

digitalWrite(RB\_in2, HIGH);

// set speed to 200 out of possible range 0~255

analogWrite(RB\_enA, 255);

//Right Front

digitalWrite(RF\_in3, HIGH);

digitalWrite(RF\_in4, LOW);

// set speed to 200 out of possible range 0~255

analogWrite(RF\_enB, 255);

// Set Left Motors to forward

//Left Front

digitalWrite(LF\_in1, LOW);

digitalWrite(LF\_in2, HIGH);

// set speed to 200 out of possible range 0~255

analogWrite(LF\_enA, 255);

//Left Back

digitalWrite(LB\_in3, HIGH);

digitalWrite(LB\_in4, LOW);

// set speed to 200 out of possible range 0~255

analogWrite(LB\_enB, 255);

delay(6000);

// Set Motors backwards

//Right Back

digitalWrite(RB\_in1, HIGH);

digitalWrite(RB\_in2, LOW);

// set speed to 200 out of possible range 0~255

analogWrite(RB\_enA, 255);

//Right Front

digitalWrite(RF\_in3, LOW);

digitalWrite(RF\_in4, HIGH);

// set speed to 200 out of possible range 0~255

analogWrite(RF\_enB, 255);

// Set Left Motors to forward

//Left Front

digitalWrite(LF\_in1, HIGH);

digitalWrite(LF\_in2, LOW);

// set speed to 200 out of possible range 0~255

analogWrite(LF\_enA, 255);

//Left Back

digitalWrite(LB\_in3, LOW);

digitalWrite(LB\_in4, HIGH);

// set speed to 200 out of possible range 0~255

analogWrite(LB\_enB, 255);